# PX-80

**MOBILE LIDAR SCANNER** 

FEATURES & TECHNICAL SPECIFICATIONS



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#### PARACOSM



#### **ABOUT**

Paracosm's PX-80 scanner is an innovative SLAM-based 3D mapping solution that incorporates LiDAR, color imagery, and IMU data to collect survey-quality point clouds quickly and accurately for a wide range of applications. PX-80 is compact, completely mobile, and capable of full 6-DoF positional tracking.

Mobile LiDAR scanning offers many advantages over aerial and conventional ground surveys, namely its flexibility, simplified workflow, and rapid data collection. This non-invasive survey method may be used day or night, indoor, outdoor, with an efficient acquisition rate of 300,000 points per second.

#### **ORDERS INCLUDE**

PX-80 LiDAR scanner & built-in processing software

Apple® iPad mini™ 4, protective case, & mount

1 hardshell storage case

1 extension pole

1 external battery, holster, & case

1 dual charger & power supply

1 power adaptor cable

1 international power adaptor

1 128 GB 3.0 USB

#### **RESULTS**

PX-80 automatically produces point clouds in full color and generates spherical images. Data is transferred via USB 3.0 from PX-80 to a workstation.

#### **FILE FORMATS**

Photosphere images (.JPEG)

RGB colorized point clouds (.LAS or .PLY)

# **PX-80**

#### **SPECIFICATIONS**

#### **PX-80**

Weight	6.4 lbs / 2.9 kg
Height	26.7 cm
Diameter	16.2 cm
Extension rod	43-67 cm

Lidar	Velodyne LiDAR°
Laser type	VLP-16, Class 1 (Eye Safe)
FOV horizontal / vertical	360° x 30° (±15°)
Acquisition rate	300,000 pts/sec
Range	0.5 m - 80 m
Relative accuracy	2-3 cm
Global accuracy	3-30 cm (10 min scan, 1 loop)
Environment	Indoor / outdoor





#### **Color Camera**

Resolution	1024p x 768p
Megapixels	3.2 MP
Maximum frame rate	50 fps
FOV horizontal / vertical	360° x 250°

Note: Accurate scans are captured by using a steady and smooth walking pace. A variety of factors can negatively influence tracking, including: rotating 6-DoF very quickly (fast 180° turns), extreme motion in the environment (a few people or vehicles in an open space are not a problem, however, scanning in a narrow hallway with multiple people is not recommended).

#### PARACOSM

# **PX-80**

#### **Internal Battery**

Туре	Lithium Ion
Battery Capacity	36 Wh
Battery Life	40 min scan time



#### **External Battery**

Туре	Lithium lon
Battery Capacity	98 Wh
Battery Life	90 min scan time



#### **Carrying Case**

#### **NANUK**

Interior dimensions (L x W x H)	20.5" x 11.3" x 7.5" 521 mm x 287 mm x 191 mm
Exterior dimensions (L x W x H)	22.0" x 14.0" x 9.0" 559 mm x 356 mm x 229 mm
Weight	11.6 lb   5.2 kg
Material	Lightweight NK-7 resin
Temperature range	Min -20°F (-29°C )   Max 140°F (60°C)
Padlock holes diameter	0.340"
Water resistant (IP67)	Yes
Airline check-in	Yes
Airline cabin carry-on	Yes











## **CAPTURE**

#### iOS Scanning App

Capture is the user interface for PX-80 which controls data collection, provides real-time scanning feedback, and post-processing options. The app connects to PX-80 via a local wireless network and does not need internet access to operate.

### RETRACE

#### **Windows Project Viewer**

Explore scans in street-view style through high resolution spherical imagery. Visit your site remotely, record progress, and organize scans by date + location.





## **PX-80**

#### **Internal Processing Software**

PX-80 has its own internal processing software which runs our proprietary SLAM algorithms on the camera, IMU, and LiDAR data and stores the captured point clouds on device.